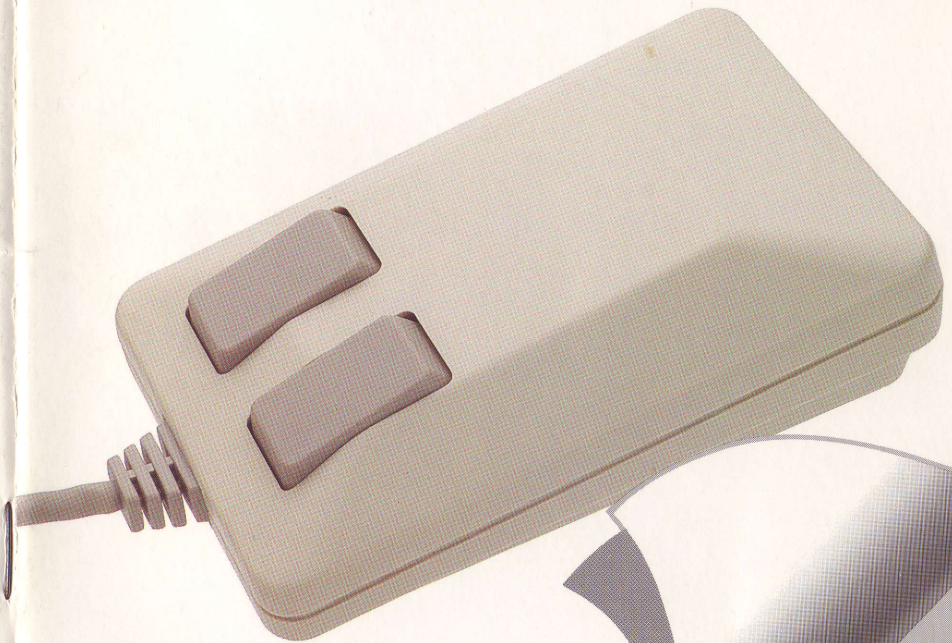


# COMMODORE<sup>®</sup> 1351 MOUSE

user's  
guide



**COMMODORE**<sup>®</sup>

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For Use With Commodore  
C64,<sup>®</sup> 64C,<sup>™</sup> C128<sup>™</sup> Computers



# 1351 MOUSE USER'S GUIDE

CAUTION: This program will auto-configure your mouse. If you have a mouse that is not auto-configured, you will need to configure it manually. For more information, see the Mouse User's Guide.

Your mouse will be automatically configured when you connect it to the computer. If you have a mouse that is not auto-configured, you will need to configure it manually. For more information, see the Mouse User's Guide.

A necessary condition for using the mouse is an expanded DOS version 3.0 or later. For more information, see the Mouse User's Guide.

The mouse is available from the U.S. Government Printing Office, Washington, D.C. 20540. Stock number 5010-108-02-1.

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### WARNING:

This equipment has been certified to comply with the limits for a Class B computing device, pursuant to subpart J of Part 15 of the Federal Communications Commission's rules, which are designed to provide reasonable protection against radio and television interference in a residential installation. If not installed properly, in strict accordance with the manufacturer's instructions, it may cause such interference. If you suspect interference, you can test this equipment by turning it off and on. If this equipment does cause interference, correct it by doing any of the following:

- Reorient the receiving antenna or AC plug.
- Change the relative positions of the computer and the receiver.
- Plug the computer into a different outlet so the computer and receiver are on different circuits.

**CAUTION:** Only peripherals with shield-grounded cables (computer input-output devices, terminals, printers, etc.), certified to comply with Class B limits, can be attached to this computer. Operation with non-certified peripherals is likely to result in communications interference.

Your house AC wall receptacle must be a three-pronged type (AC ground). If not, contact an electrician to install the proper receptacle. If a multi-connector box is used to connect the computer and peripherals to AC, the ground must be common to all units.

If necessary, consult your Commodore dealer or an experienced radio-television technician for additional suggestions. You may find the following FCC booklet helpful: "How to Identify and Resolve Radio-TV Interference Problems." The booklet is available from the U.S. Government Printing Office, Washington, D.C. 20402, stock no. 004-000-00345-4.

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## ABOUT THIS MANUAL

Basically, this manual is divided into two parts. The first part includes the introduction, mouse cleaning, and tips for general care of the mouse. That part is for the user with mouse-compatible software, who wants simply to plug in the mouse and begin using it. The second part of the manual contains information needed by those who wish to develop software for the mouse.

## INTRODUCTION

The Commodore 1351 Mouse™ is a controller designed for use with the Commodore 64® or Commodore 128™ computers. It features two buttons on the top, and a ball on the underside that is rolled upon a flat surface to manipulate onscreen activity.

The mouse has two modes of operation—joystick mode and proportional mode.

In joystick mode, the mouse emulates a joystick and can be used with all joystick-compatible software. In this mode, the left button is the fire button and the right button is usually ignored.

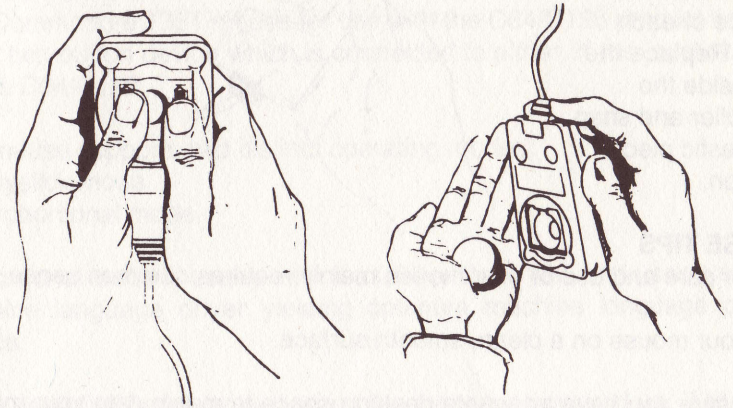
In proportional mode, the mouse uses a new technique to communicate mouse movement to the controlling application software. That requires the software to know the mouse is there and how to read it. For example, the GEOS™ operating system can use many different input drivers. One of them is the Commodore Mouse driver, which can be used with the 1351 in proportional mode.

The 1351 provides proportional mode so that applications can have a fast, responsive pointer that moves easily on the screen. Joystick mode acts as a fallback for those applications that don't have installable device drivers. Therefore, you can use the mouse as a joystick for older software, and take advantage of the benefits provided by proportional mode with newer applications.

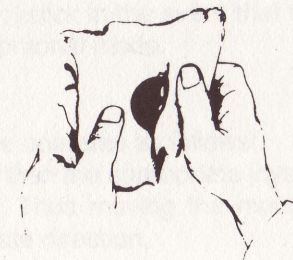
The mouse automatically powers up in proportional mode. To choose joystick mode, plug the mouse into either joystick port on the side of the computer and hold down the right button as the computer is powered up.

## MOUSE CLEANING

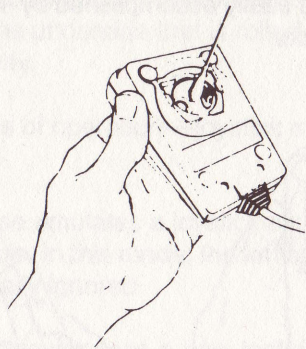
Since the ball of your mouse must roll freely to accurately manipulate the cursor (or whatever) on the screen, it's important that the ball remain free of dirt or debris. This is easily accomplished by sliding out the plastic piece holding the ball in place.



Remove the ball and wipe it off with a soft cloth, such as a handkerchief.



To remove any dirt or dust from the ball area, just blow gently into the opening. Around the top of the opening, there are three metal rollers. To clean these, take a cotton-tipped swab, moistened with head cleaning fluid or alcohol, and gently clean the surface of each roller. Replace the ball inside the controller and snap the plastic piece back on.



### MOUSE TIPS

Proper care and use of your mouse mainly requires common sense.

Use your mouse on a clean, smooth surface.

Make sure you have adequate desktop space to manipulate your mouse, so you don't have to constantly pick up and reposition it.

Don't hold the mouse by its cord, or let the body of the mouse hang off the table.

## PROPORTIONAL MOUSE DEVELOPER'S GUIDE

This section explains the theory of operation of the Commodore 1351 mouse and suggests software strategies for interfacing to it.

### INTRODUCTION

The Commodore 1351 mouse for use with the C64/C128 product line is a small two-button device which is connected to either of the joystick ports on the C64/C128.

The mouse supports two distinct operating modes:

- 1) Joystick mode.
- 2) Proportional mode.

Proportional mode is usable with the C64 or the C128, and uses a special machine language driver yielding optimum machine language performance.

Mode selection is determined when the mouse is powered up. If the user depresses the right mouse button when the device is powered up, then the mouse will be in joystick mode.

If the user does not depress the right mouse button when the device is powered up, then the mouse will default to proportional mode.

It is the intent of joystick mode to provide a mode of operation where the mouse can be used as a joystick in the event that the software being run does not support the proportional mode.

### JOYSTICK MODE

In joystick mode the mouse operates as follows:

- 1) If the mouse is moved, then the appropriate joystick lines are activated for a period of 20 ms. Thus moving the mouse is like pushing the joystick in the appropriate direction.
- 2) The left mouse button is mapped to what would be the fire button on a joystick.
- 3) The right mouse button is mapped into the SID POTX register. If the button is depressed then the SID POTX register will contain a number  $< \$80$ . If the button is not depressed then SID POTX will contain a number  $\geq \$80$ .
- 4) See the section on SID REGISTER CAUTIONS.

### Software interface:

For most applications, the interface for joystick mode of operation shall be just as any joystick driver, and the right button shall be ignored.

### PROPORTIONAL MODE

In proportional mode the mouse operates as follows:

- 1) Mouse movement is tracked internally to the mouse. The position of the mouse MOD 64 is transmitted to the SID POTX and POTY registers every 512 us., requiring no software intervention.

The POTX register is used to read the X position of the mouse and the POTY register is used to read the Y position of the mouse.

The register contents are as follows:

Bit Position	7	6	5	4	3	2	1	0
POT Register	X	P5	P4	P3	P2	P1	P0	N

where:

- X . . . . . is a don't care bit.
- P5-P0 . . . . . is the mouse position MOD 64.
- N . . . . . is a special (noise) bit (keep reading . . .).

- 2) The left mouse button is mapped to what would be the fire button on a joystick.
- 3) The right mouse button is mapped to what would be the UP direction on a joystick.

### Software interface:

- 1) Because the left and right buttons appear as joystick lines, reading them from software is a trivial exercise in polling.

Note that as with a joystick, the buttons will interfere with the keyboard map, and software should make some effort to distinguish between a point short in the keyboard matrix (i.e., a key being depressed), and a whole row or column being grounded (i.e., a joystick type of signal).

- 2) The position information is not difficult to handle. It fits ideally in the 60 hz interrupt routine (preferably at the beginning—see the section on SID REGISTER CAUTIONS).

The strategy is as follows:

- 1) Read the mouse position MOD 64.
- 2) Determine if the mouse has moved by comparing the current position with a saved copy of the previous position.
- 3) If the mouse has moved, then modify your pointer position appropriately.

The mouse makes an effort to transmit a position to the SID register. Unfortunately, there is a single bit of noise in the transmission.

For example, even if the mouse is still, it is possible for the POT register to vacillate between \$80 and \$7F. This would result in the mouse position as jittering between two points.

It is therefore necessary to consider the low order bit of the POT register before making any decision as to whether the mouse has moved.

All of this can be seen in the supplied mouse driver code.

### SID REGISTER CAUTIONS:

In the C64 & C128, the SID pot lines are connected to both joystick ports. A 4066 analog switch is used to switch the POT lines between the two ports based on one of the keyboard scan lines. This means that the normal keyscan interrupt temporarily affects the values returned in the POT registers. Therefore, in order to perform reliable conversions, the POT lines must be connected to the mouse for a period of >1.6 ms before the value returned in the POT register is valid.

The best way to insure this is to wedge the mouse driver software into the IRQ handler prior to the polled keyscan. This more-or-less assures that the keyscan lines have been sufficiently stable before the POT register is read by the mouse drivers.

**BASIC AND MACHINE  
LANGUAGE PROGRAMS  
FOR 1351 MOUSE  
AND C64**

```
100 GOSUB140:GOSUB330
110 V = 13*4096:POKEV + 21,1:POKEV + 39,1:POKEV +
    0,100:POKEV + 1,100:POKEV + 16,0
120 POKE2040,56:SYS12*4096 + 256
130 END
140 FORX = 0TO129:READA$:GOSUB430:POKE49408 + X,Y:NEXTX:
    RETURN
150 DATAAD,15,03,C9,C1,F0,19,08
160 DATA78,AD,14,03,8D,00,C0,AD
170 DATA15,03,8D,01,C0,A9,21,8D
180 DATA14,03,A9,C1,8D,15,03,28
190 DATA60,D8,AD,19,D4,AC,02,C0
200 DATA20,58,C1,8C,02,C0,18,6D
210 DATA00,D0,8D,00,D0,8A,69,00
220 DATA29,01,4D,10,D0,8D,10,D0
230 DATAAD,1A,D4,AC,03,C0,20,58
240 DATAAC1,8C,03,C0,38,49,FF,6D
250 DATA01,D0,8D,01,D0,6C,00,C0
260 DATA8C,05,C0,8D,04,C0,A2,00
270 DATA38,ED,05,C0,29,7F,C9,40
```

```
280 DATAB0,07,4A,F0,12,AC,04,C0
290 DATA60,09,C0,C9,FF,F0,08,38
300 DATA6A,A2,FF,AC,04,C0,60,A9
310 DATA00,60
320 REM-----
330 FORX = 0TO63:READA$:GOSUB430:POKE3584 + X,Y:NEXTX:
    RETURN
340 DATAF8,00,00,90,00,00,B8,00
350 DATA00,DC,00,00,8E,00,00,07
360 DATA00,00,02,00,00,00,00,00
370 DATA00,00,00,00,00,00,00,00
380 DATA00,00,00,00,00,00,00,00
390 DATA00,00,00,00,00,00,00,00
400 DATA00,00,00,00,00,00,00,00
410 DATA00,00,00,00,00,00,00,00
420 REM-----
430 Y = 1:Y1 = 0
440 IFLEFT$(A$,1)<>MID$("0123456789ABCDEF",Y,1)
    THENY = Y + 1:GOTO440
450 Y1 = (Y-1)*16:Y = 1
460 IFRIGHT$(A$,1)<>MID$("0123456789ABCDEF",Y,1)
    THENY = Y + 1:GOTO460
470 Y = Y1 + Y-1:RETURN
```

READY.

```

1 ;
2 ;
3 ;
4 ;
5 iirg = $0314
6 vic = $d000
7 sid = $d400
8 potx = sid+$19
9 poty = sid+$1a
10 vicdata = $d000 ; vic registers
11 xpos = vicdata+$00 ; low order x position
12 ypos = vicdata+$01 ; y position
13 xposmsb = vicdata+$10 ; bit 0 is high order x position
14
15
16 *=$c000
17
18 iirg2 *=$+2
19 opotx *=$+1
20 opoty *=$+1
21 newvalue *=$+1
22 oldvalue *=$+1
23
24 * = $c100
25
26 install lda iirg+1
27 cmp #>mirq
28 beq 90$
29 php
30 sei
31 lda iirg
32 sta iirg2
33 lda iirg+1
34 sta iirg2+1
35
36 lda #<mirq
37 sta iirg
38 lda #>mirq
39 sta iirg+1
40
41 plp
42 rts

```

```

C/64 mouse driver for BASIC 2.0 applications

```

=0314			
=D000			
=D400			
=D419			
=D41A			
=D000			
=D000			
=D001			
=D010			
=C000			
=C002			
C002			
C003			
C004			
C005			
C005			
=C100			
AD 0315			
C100			
C103			
C105			
C107			
C108			
C109			
C10C			
C10F			
C112			
C115			
C117			
C11A			
C11C			
C11F			
C120			
D8			
AD D419			
AC C002			
20 C158			
8C C002			
18			
6D D000			
8D D000			
8A			
C135			
69 00			
29 01			
4D D010			
8D D010			
AD D41A			
AC C003			
20 C158			
8C C003			
38			
49 FF			
6D D001			
8D D001			
6C C000			

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```

D8			
AD D419			
AC C002			
20 C158			
8C C002			
18			
6D D000			
8D D000			
8A			
C135			
69 00			
29 01			
4D D010			
8D D010			
AD D41A			
AC C003			
20 C158			
8C C003			
38			
49 FF			
6D D001			
8D D001			
6C C000			

```

; just in case.....
; get delta values for x
; modify low order x position
; get delta value for y
; modify y position ( decrease y for increase in pot )
; continue w/ irq operation

```

43	mirg	cld	
44		lda potx	
45		ldy opotx	
46		jsr movchk	
47		sty opotx	
48			
49		clc	
50		adc xpos	
51		sta xpos	
52		txa	
53		adc #500	
54		and #00000001	
55		eor xposmsb	
56		sta xposmsb	
57			
58		lda poty	
59		ldy opoty	
60		jsr movchk	
61		sty opoty	
62			
63		sec	
64		eor #5ff	
65		adc ypos	
66		sta ypos	
67			
68		jmp (iirg2)	
69	90\$		



```

70 ; movchk
71 entry y = old value of pot register
72 ; a = current value of pot register
73 ; y = value to use for old value
74 ; x, a = delta value for position
75 ;
76
77 movchk sty oldvalue save old & new values
78 sta newvalue preload x w/ 0
79 ldx #0
80
81 sec a <= mod64( new-old )
82 sbc oldvalue
83 and #01111111
84 cmp #01000000 if > 0
85 bcs 50$
86 lsr a a <= a/2
87 beq 80$ if < 0
88 ldy newvalue y <= newvalue
89 rts return
90
91 50$ ora #011000000 else or in high order bits
92 cmp #0$ if < -1
93 beg 80$
94 sec a <= a/2
95 ror a x <= -1
96 ldx #0$ y <= newvalue
97 ldy newvalue
98 rts return
99
100 80$ lda #0 a <= 0
101 rts return w/ y = old value
102

```

\* \* Cross Reference \* \*

Reference flags	(# = Definition, \$ = Write, <BLANK> = Read)
Symbol	Value
IIRQ	=0314
IIRQ2	C000
INSTALL	C100
MIRQ	C121
MOVCHK	C158
NEWVALUE	C004
OLDVALUE	C005
OPOTX	C002
OPOTY	C003
POTX	=D419
POTY	=D41A
SID	=D400
VIC	=D000
VICDATA	=D000
XPOS	=D000
XPOSMSB	=D010
YPOS	=D001

References	5#	26	31	33	37\$	39\$
18#	32\$	34\$	69			
27	36	38	44#			
47	61	77#				
21#	78\$	88	97			
22#	77\$	82				
19#	46	48\$				
20#	60	62\$				
8#	45					
9#	59					
7#	8					
6#						
11#	12	13	14			
12#	51	52\$				
14#	56	57\$				
13#	66	67\$				

**BASIC AND MACHINE  
LANGUAGE PROGRAMS  
FOR 1351 MOUSE  
AND C128**

```

100 GOSUB230:GOSUB420:SYS6144
120 BA = DEC("0A04"):POKE BA,1ORPEEK(BA)
130 SPRITE 1,1,2:MOVSPR 1,100,100
140 GRAPHIC1,1:CHAR 1,8,1,"1351 MOUSE PAINT"
150 DO:IF (JOY(1) AND 128) THEN GOSUB 180
160 IF (JOY(1) AND 1) THEN GRAPHIC 1,1:CHAR 1,8,1, "1351 MOUSE PAINT"
170 LOOP
180 X = RSPPOS(1,0) - 25:Y = RSPPOS(1,1) - 51:X = - X*(X>0):Y = - Y*(Y>0)
190 LOCATE X,Y: C = 1 - RDOT(2):DRAW C,X,Y
200 DO:X = RSPPOS(1,0) - 25:Y = RSPPOS(1,1) - 51:
   X = - X*(X>0):Y = - Y*(Y>0)
210 DRAW C TO X,Y:LOOP WHILE JOY(1) AND 128 : RETURN
220 REM-----
230 FORX = 0TO135:READA$:POKE6144 + X,DEC(A$):NEXTX:
   RETURN
240 DATAAD,15,03,C9,18,F0,19,08
250 DATA78,AD,14,03,8D,F0,18,AD
260 DATA15,03,8D,F1,18,A9,21,8D
270 DATA14,03,A9,18,8D,15,03,28

```

```

280 DATA60,D8,AD,7E,11,D0,33,AD
290 DATA19,D4,AC,F2,18,20,5D,18
300 DATA8C,F2,18,18,6D,D6,11,8D
310 DATAD6,11,8A,69,00,29,01,4D
320 DATAE6,11,8D,E6,11,AD,1A,D4
330 DATAAC,F3,18,20,5D,18,8C,F3
340 DATA18,38,49,FF,6D,D7,11,8D
350 DATAD7,11,6C,F0,18,8C,F5,18
360 DATA8D,F4,18,A2,00,38,ED,F5
370 DATA18,29,7F,C9,40,B0,07,4A
380 DATAF0,12,AC,F4,18,60,09,C0
390 DATAAC9,FF,F0,08,38,6A,A2,FF
400 DATAAC,F4,18,60,A9,00,60,00
410 REM-----
420 FORX = 0TO63:READA$:POKEDEC("0E00") + X,DEC(A$):NEXTX:
   RETURN
430 DATAF8,00,00,90,00,00,B8,00
440 DATA00,DC,00,00,8E,00,00,07
450 DATA00,00,02,00,00,00,00,00
460 DATA00,00,00,00,00,00,00,00
470 DATA00,00,00,00,00,00,00,00
480 DATA00,00,00,00,00,00,00,00
490 DATA00,00,00,00,00,00,00,00
500 DATA00,00,00,00,00,00,00,00

```

1 ; C/128 mouse driver for BASIC 7.0 applications  
 2 ;  
 3 ;

```

4
5 =0314
6 = $0000
7 vic = $d000
8 sid = $d400
9 potx = sid+$19
10 poty = sid+$1a
11 active = $117e ; if zero, then move sprite
12 vicdata = $11d6 ; basic's copy of vic register image
13 xpos = vicdata+$00 ; low order x position
14 ypos = vicdata+$01 ; y position
15 xposmsb = vicdata+$10 ; bit 0 is high order x position
16
17 *= $18f0
18
19
20 iirg2 *= $+2
21 opotx *= $+1
22 opoty *= $+1
23 newvalue *= $+1
24 oldvalue *= $+1
25
26 * = $1800
27
28 install lda iirg+1
29 cmp #>iirg
30 beq 90$
31 plp
32 sei
33 lda iirg
34 sta iirg2
35 lda iirg+1
36 sta iirg2+1
37
38 lda #<iirg
39 sta iirg
40 lda #>iirg
41 sta iirg+1
42
43 plp
44 rts
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57
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73
90$

```

```

1821 D8
1822 AD 117E
1825 D0 33
1827 AC D419
182A AC 18F2
182D 20 185D
1830 8C 18F2
1833 18
1834 6D 11D6
1837 8D 11D6
183A 8A
183B 69 00
183D 29 01
183F 4D 11E6
1842 8D 11E6
1845 AD D41A
1848 AC 18F3
184B 20 185D
184E 8C 18F3
1851 38
1852 49 FF
1854 6D 11D7
1857 8D 11D7
185A 6C 18F0
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90$

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62
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66
67
68
69
70
71
72
73
90$

```

```

74 ; movchk
75 entry Y = old value of pot register
76 a = current value of pot register
77 y = value to use for old value
78 x,a = delta value for position
79 ;
80
81 movchk sty oldvalue save old & new values
82 sta newvalue preload x w/ 0
83 ldx #0 a <= mod64( new-old )
84
85 sec oldvalue
86 sbc oldvalue
87 and #%01111111 if > 0
88 cmp #%01000000
89 bcs 50$
90 lsr a a <= a/2
91 beq 80$ if <> 0
92 ldy newvalue y <= newvalue
93 rts return
94
95 50$ ora #%11000000 else or in high order bits
96 cmp #0$ if <> -1
97 beq 80$
98 sec
99 ror a
100 ldx #0$ff x <= -1
101 ldy newvalue y <= newvalue
102 rts return
103
104 80$ lda #0 a <= 0
105 rts return w/ y = old value
106

```

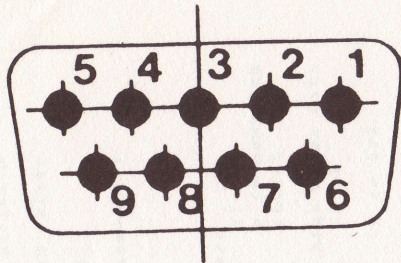
Reference flags (# = Definition, \$ = Write, <BLANK> = Read)

Symbol	Value
ACTIVE	=117E
IIRQ	=0314
IIRQ2	18F0
INSTALL	1800
MIRQ	1821
MOVCHK	185D
NEWVALUE	18F4
OLDVALUE	18F5
OPOTX	18F2
OPOTY	18F3
POTX	=D419
POTY	=D41A
SID	=D400
VIC	=D000
VICDATA	=11D6
XPOS	=11D6
XPOSMSB	=11E6
YPOS	=11D7

References	
11#	47
5#	28
20#	34\$
28#	33
29	36\$
51	40
23#	65
24#	81#
21#	82\$
22#	92
8#	85
9#	81\$
7#	50
6#	52\$
13#	64
14#	66\$
16#	49
15#	63
	8
	9
	14
	15
	55
	56\$
	60
	61\$
	70
	71\$

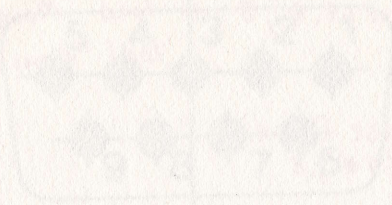
	35	39\$	41\$
	73		
	46#		
	101		

# 1350 MOUSE PIN-OUT



CONNECTION TABLE		
FUNCTION		
PIN NO.	JOYSTICK MODE	PROPORTIONAL MODE
1	UP	RIGHT BUTTON
2	DOWN	UNUSED
3	LEFT	UNUSED
4	RIGHT	UNUSED
5	UNUSED	Y-POSITION
6	LEFT BUTTON	LEFT BUTTON
7	+5V	+5V
8	GND	GND
9	RIGHT BUTTON	X-POSITION

1350 MOUSE PPM CAT



CONNECTION TABLE

PORT NO.	KEYS ON MOUSE	PROPORTIONAL REL.
1	UP	RIGHT BUTTON
2	DOWN	UNDEF
3	LEFT	UNDEF
4	RIGHT	UNDEF
5	UNDEF	POSITION
6	LEFT BUTTON	LEFT BUTTON
7	UNDEF	UNDEF
8	UNDEF	UNDEF
9	RIGHT BUTTON	POSITION